

Section 4.5

Problem 3 Find both a basis for the row space and a basis for the column space of:

$$\begin{bmatrix} 1 & -4 & -3 & -7 \\ 2 & -1 & 1 & 7 \\ 1 & 2 & 3 & 11 \end{bmatrix}$$

Answer:

Row operations:

$$\begin{array}{l} \xrightarrow{-2R_1 + R_2} \\ \xrightarrow{-R_1 + R_3} \end{array} \begin{bmatrix} 1 & -4 & -3 & -7 \\ 0 & 7 & 7 & 21 \\ 0 & 6 & 6 & 18 \end{bmatrix} \xrightarrow{\begin{array}{l} \frac{1}{7}R_2 \\ \frac{1}{6}R_3 \end{array}} \begin{bmatrix} 1 & -4 & -3 & -7 \\ 0 & 1 & 1 & 3 \\ 0 & 1 & 1 & 3 \end{bmatrix}$$

$$\xrightarrow{-R_2 + R_3} \begin{bmatrix} 1 & -4 & -3 & -7 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{4R_2 + R_1} \begin{bmatrix} 1 & 0 & 1 & 5 \\ 0 & 1 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} = E$$

reduced echelon form

A basis for the row space is

$$\left\{ \begin{bmatrix} 1 & 0 & 1 & 5 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 1 & 3 \end{bmatrix} \right\}$$

For the column space, we need to identify the pivot columns, which are 1 and 2.

\Rightarrow A basis for the column space is:

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -4 \\ -1 \\ 2 \end{bmatrix} \right\}$$

Problem 17: Find a basis T for \mathbb{R}^3 that contains the vectors $v_1 = (1, 2, 2)$, and $v_2 = (2, 3, 3)$

Answer: Consider $\{v_1, v_2, e_1, e_2, e_3\}$

This is a linearly dependent set that spans \mathbb{R}^3 . Use algorithm used in class to extract a basis from that list containing v_1, v_2 . Form the matrix A with those as its column vectors

$$A = \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 2 & 3 & 0 & 1 & 0 \\ 2 & 3 & 0 & 0 & 1 \end{bmatrix}$$

and proceed by row operations:

$$\begin{array}{l} \xrightarrow{-2R_1+R_2} \\ \xrightarrow{-2R_1+R_3} \end{array} \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 0 & -1 & -2 & 1 & 0 \\ 0 & -1 & -2 & 0 & 1 \end{bmatrix} \xrightarrow{-R_1+R_2} \begin{bmatrix} 1 & 2 & 1 & 0 & 0 \\ 0 & -1 & -2 & 1 & 0 \\ 0 & 0 & 0 & -1 & 1 \end{bmatrix}$$

This is already in echelon form (not reduced), and the pivot columns are 1, 2, and 4.
 \Rightarrow A basis T for \mathbb{R}^3 containing v_1, v_2 is

$$T = \{v_1, v_2, e_2\}.$$