

5-input-output-relation

June 13, 2023

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[1]: from sympy import *  
from DifferentialAlgebra import *  
init_printing ()
```

```
[2]: t, k12, k21, Ve, ke = var ('t, k_12, k_21, V_e, k_e')  
params = [k12, k21, ke, Ve]  
params
```

```
[2]: [k12, k21, ke, Ve]
```

```
[3]: x1, x2, y, u = function ('x_1, x_2, y, u')
```

```
[4]: R = DifferentialRing (derivations = [t], blocks = [y, x1, x2, u, params],  
parameters = params)
```

```
[5]: syst = [ Eq(Derivative(x1(t),t), -k12*x1(t) + k21*x2(t) - Ve*x1(t)/(ke+x1(t)) +  
↪u(t)),  
Eq(Derivative(x2(t),t), k12*x1(t) - k21*x2(t)),  
Eq(y(t),x1(t))]  
A_R = RegularDifferentialChain (syst, R)  
A_R.equations (solved=True)
```

```
[5]: 
$$\left[ x_1(t) = -\frac{-k_{21}x_2(t) - \frac{d}{dt}x_2(t)}{k_{12}}, \frac{d}{dt}x_1(t) = \frac{-V_e x_1(t) - k_{12}k_e x_1(t) - k_{12}x_1^2(t) + k_{21}k_e x_2(t) + k_{21}x_1(t)x_2(t)}{k_e + x_1(t)} \right]$$

```

```
[6]: S = DifferentialRing (derivations = [t],  
blocks = [x1, x2, y, u, params],  
parameters = params)
```

```
[7]: A_S = A_R.change_ranking (S)  
A_S.equations (solved=True)
```

```
[7]: 
$$\left[ \frac{d^2}{dt^2}y(t) = \frac{-V_e k_{21} k_e y(t) - V_e k_{21} y^2(t) - V_e k_e \frac{d}{dt}y(t) - k_{12} k_e^2 \frac{d}{dt}y(t) - 2k_{12} k_e y(t) \frac{d}{dt}y(t) - k_{12} y^2(t) \frac{d}{dt}y(t) + k_{21} k_e^2 u(t)}{\dots} \right]$$

```

```
[8]: leader = var ('leader')  
IO_rel = A_S.equations (selection = Eq(leader,Derivative(y(t),t,t)))[0]
```

```
I0_rel
```

[8]:
$$\begin{aligned} & V_e k_{21} k_e y(t) + V_e k_{21} y^2(t) + V_e k_e \frac{d}{dt} y(t) + k_{12} k_e^2 \frac{d}{dt} y(t) + 2k_{12} k_e y(t) \frac{d}{dt} y(t) + k_{12} y^2(t) \frac{d}{dt} y(t) - k_{21} k_e^2 u(t) + \\ & k_{21} k_e^2 \frac{d}{dt} y(t) - 2k_{21} k_e u(t) y(t) + 2k_{21} k_e y(t) \frac{d}{dt} y(t) - k_{21} u(t) y^2(t) + k_{21} y^2(t) \frac{d}{dt} y(t) - k_e^2 \frac{d}{dt} u(t) + \\ & k_e^2 \frac{d^2}{dt^2} y(t) - 2k_e y(t) \frac{d}{dt} u(t) + 2k_e y(t) \frac{d^2}{dt^2} y(t) - y^2(t) \frac{d}{dt} u(t) + y^2(t) \frac{d^2}{dt^2} y(t) \end{aligned}$$

[9]: `I0_rel = I0_rel / S.initial (I0_rel)`
`I0_rel`

[9]:
$$\frac{V_e k_{21} k_e y(t) + V_e k_{21} y^2(t) + V_e k_e \frac{d}{dt} y(t) + k_{12} k_e^2 \frac{d}{dt} y(t) + 2k_{12} k_e y(t) \frac{d}{dt} y(t) + k_{12} y^2(t) \frac{d}{dt} y(t) - k_{21} k_e^2 u(t) + k_{21} k_e^2 \frac{d}{dt} y(t)}{k_e + y(t)}$$

[10]: `I0_rel_integrated = S.integrate (I0_rel, t)`
`I0_rel_integrated`

[10]:
$$\left[\frac{V_e k_{21} y(t) - k_{21} k_e u(t) - k_{21} u(t) y(t) - k_e \frac{d}{dt} u(t) - y(t) \frac{d}{dt} u(t)}{k_e + y(t)}, \frac{-V_e k_e - k_{12} k_e^2 + k_{12} y^2(t) - k_{21} k_e^2 + k_{21} y^2(t)}{k_e + y(t)}, y(t) \right]$$

[11]: `I0_rel_integrated = I0_rel_integrated[0] + \`
`Derivative (I0_rel_integrated[1], t) + \`
`Derivative (I0_rel_integrated[2], t, t)`
`I0_rel_integrated`

[11]:
$$\frac{\partial}{\partial t} \frac{-V_e k_e - k_{12} k_e^2 + k_{12} y^2(t) - k_{21} k_e^2 + k_{21} y^2(t)}{k_e + y(t)} + \frac{d^2}{dt^2} y(t) + \frac{V_e k_{21} y(t) - k_{21} k_e u(t) - k_{21} u(t) y(t) - k_e \frac{d}{dt} u(t) - y(t) \frac{d}{dt} u(t)}{k_e + y(t)}$$

[12]: `simplify (I0_rel / S.initial (I0_rel) - I0_rel_integrated.doit())`

[12]: 0

[]: