

# Two Applications of Topology to Convex Geometry

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**Abstract**— The purpose of this paper is to prove two theorems of convex geometry using the techniques of topology. The first theorem states that if, for a strictly convex body  $K$ , one may choose continuously a centrally symmetric section, then  $K$  must be centrally symmetric. The second theorem states that if every section of a three-dimensional convex body  $K$  through the origin has an axis of symmetry, then there is a section of  $K$  through the origin which is a disk.

## 1. A SHAKEN ROGERS THEOREM

Let  $K$  be a convex body and let  $p_0$  be a point. Suppose that every section of  $K$  through  $p_0$  is centrally symmetric. Then, Rogers proved in [5] that  $K$  is centrally symmetric, although  $p_0$  may not be the center of  $K$ . If this is the case, Aitchison, Petty, and Rogers [1] and Larman [2] proved that  $K$  must be an ellipsoid. The purpose of this section is to prove a shaken version of the Rogers theorem; that is, we essentially prove that if, for every direction, one can choose continuously a section of  $K$  that is centrally symmetric, then  $K$  is centrally symmetric.

Let  $\delta: S^2 \rightarrow \mathbb{R}$  be a continuous function such that  $\delta(-x) = -\delta(x)$ . Let us denote by  $[\delta]$  the following set of hyperplanes in  $\mathbb{R}^3$ :

$$[\delta] = \{H_y^\delta = \{x \in \mathbb{R}^3 \mid x \cdot y = \delta(y)\}\}_{y \in S^2}.$$

If this is the case, we say that  $[\delta]$  is a 2-cycle of planes in  $E^3$ . This 2-cycle should be considered as a subset of the Grassmannian manifold  $G(3, 4) = P^3$  (identifying  $E^3$  with a hyperplane of  $E^4$  that does not contain the origin and every plane of  $E^3$  with the hyperplane of  $E^4$  that passes through the origin and contains the plane). The cohomology ring  $H^*(G(3, 4), Z_2) = \{Z_2[x]; \kappa^4 = 0\}$ , where the generator  $\kappa \in H^1(G(3, 4), Z_2) = Z_2$ , by duality, can be realized through every 2-cycle of planes.

Let now  $K \subset E^3$  be a convex body and, for every  $y \in S^2$ , let  $K_y^\delta = K \cap H_y^\delta$ . We say that  $\{K_y^\delta\}_{y \in S^2}$  is a 2-cycle of sections of  $K$  if

$$K_x^\delta \cap K_y^\delta \cap \text{int}(K) \neq \emptyset$$

for every  $x, y \in S^2$ .

**Lemma 1.1.** *Let  $[\delta_1]$  and  $[\delta_2]$  be two 2-cycles of planes in  $E^3$  and let  $p \in E^3$ . Then, there is  $x_0 \in S^2$  such that  $p \in H_{x_0}^{\delta_1} = H_{x_0}^{\delta_2}$ .*

**Proof.** Let  $[\delta_3]$  be the 2-cycle of planes that pass through  $p$ . It is enough to prove that  $[\delta_1] \cap [\delta_2] \cap [\delta_3] \neq \emptyset$ , that is, that there exists  $x_0 \in S^2$  such that  $H_{x_0}^{\delta_1} = H_{x_0}^{\delta_2} = H_{x_0}^{\delta_3}$ ; but this is true because any 2-cycle of planes realizes the generator  $\kappa \in H^1(G(3, 4), Z_2) = Z_2$  and we know that  $\kappa^3$ , the generator of  $H^3(G(3, 4), Z_2) = Z_2$ , is not zero.

**Lemma 1.2.** *Let  $[\delta]$  be a 2-cycle of planes in  $E^3$  and let  $L$  be a line in  $E^3$ . Then, there is  $x_0 \in S^2$  such that  $L \subset H_{x_0}^\delta$ .*

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**Proof.** Let  $p_1$  and  $p_2$  be two different points of  $L$  and let  $[\delta_i]$  be the 2-cycle of planes that pass through  $p_i$ ,  $i = 1, 2$ . As in the above lemma, we have  $[\delta_1] \cap [\delta_2] \cap [\delta] \neq \emptyset$ ; that is, there exists  $x_0 \in S^2$  such that  $L \subset H_{x_0}^\delta$ .

**Theorem 1.1.** *Let  $K$  and  $L$  be strictly convex bodies and let  $\delta_i$  be such that  $\{K_y^{\delta_1}\}_{y \in S^2}$  is a 2-cycle of sections of  $K$  and  $\{L_y^{\delta_2}\}_{y \in S^2}$  is a 2-cycle of sections of  $L$ . Suppose that, for every  $x \in S^2$ ,*

$$K_{x_0}^{\delta_1} \text{ is a translation of } L_{x_0}^{\delta_2}.$$

*Then,  $K$  is a translation of  $L$ .*

**Proof.** Let  $\aleph$  be the set of diametral lines of  $K$ . Since  $K$  is a strictly convex body, there is exactly one diametral line in every direction. Note first that, by Lemma 1.1, if  $\ell$  is a diametral line of  $K$ , then there is  $x \in S^2$  such that  $\ell \subset H_x^{\delta_1}$ .

We start proving that there are  $x_0 \neq y_0 \in S^2$  such that  $H_{x_0}^{\delta_1} \cap H_{y_0}^{\delta_1}$  is a diametral line of  $K$ . Suppose not. Then, for every diametral line  $\ell$  of  $K$ , there is a unique plane  $H \in [\delta_1]$  such that  $\ell \subset H$ . Define  $\varphi: \aleph \rightarrow [\delta_1]$  in such a way that  $\varphi(\ell) \in [\delta_1]$  is the unique plane of  $[\delta_1]$  that contains the diametral line  $\ell$ . Note that  $\varphi$  is continuous. To see this, suppose that  $\ell_i \rightarrow \ell$  but  $\varphi(\ell_i) \nrightarrow \varphi(\ell)$ . Since  $[\delta_1]$  is compact, there is a subsequence  $\varphi(\ell_{i_j})$  such that  $\varphi(\ell_{i_j}) \rightarrow H$  in  $[\delta_1]$  but  $\varphi(\ell) \neq H$ . By hypothesis,  $\ell_{i_j} \subset \varphi(\ell_{i_j})$ , which implies that  $\ell \subset H$ ; hence, by the definition of  $\varphi$ ,  $\varphi(\ell) = H$ , which is a contradiction. This proves that  $\varphi$  is continuous. Next, to every plane  $\Gamma$  through the origin, we associate continuously a line  $\Phi(\Gamma) \subset \Gamma$  as follows: let  $\Gamma$  be a plane through the origin and let  $\ell \in \aleph$  be orthogonal to  $\Gamma$ ; define  $\Phi(\Gamma)$  as the unique line through the origin contained in  $\Gamma$  that is parallel to  $\Gamma \cap \varphi(\ell)$ . Clearly, the map  $\Gamma \rightarrow \Phi(\Gamma)$  is continuous, but this is impossible. Then, there exist  $x_0 \neq y_0 \in S^2$  such that  $\mathcal{L} = H_{x_0}^{\delta_1} \cap H_{y_0}^{\delta_1}$  is a diametral line of  $K$ .

Let  $\mathcal{L}'$  be the diametral line of  $L$  parallel to  $\mathcal{L}$ . Then, we have  $\text{length}(\mathcal{L} \cap K) = \text{length}(\mathcal{L}' \cap L)$ . If not, suppose, without loss of generality, that  $\text{length}(\mathcal{L} \cap K) < \text{length}(\mathcal{L}' \cap L)$ . Hence, by Lemma 1.2, there is  $z_0 \in S^2$  such that  $\mathcal{L}' \subset H_{z_0}^{\delta_2}$ . If this is so,  $\mathcal{L}'$  is also a diametral line of  $L_{z_0}^{\delta_2}$ , and by hypothesis, since  $L_{z_0}^{\delta_2}$  is a translation of  $K_{z_0}^{\delta_1}$ , there is a chord of  $K$  whose length is the length of  $\mathcal{L}' \cap L$ , which contradicts the fact that  $\mathcal{L}$  is the diametral line of  $K$ . By the same arguments and since  $L$  is strictly convex, we have  $\mathcal{L}' = H_{x_0}^{\delta_2} \cap H_{y_0}^{\delta_2}$ .

Assume, without loss of generality, perhaps after a translation of  $L$ , that  $K_{x_0}^{\delta_1} = L_{x_0}^{\delta_2}$  and  $K_{y_0}^{\delta_1} = L_{y_0}^{\delta_2}$ . Therefore,  $H_{x_0}^{\delta_1} = H_{x_0}^{\delta_2}$ ,  $H_{y_0}^{\delta_1} = H_{y_0}^{\delta_2}$ , and  $\mathcal{L} = \mathcal{L}'$ . We will prove that  $K = L$ . For this purpose, it will be enough to prove that  $\text{bd } K \subset \text{bd } L$ . Let  $p \in \text{bd } K$  and, by Lemma 1.1, let  $w_0 \in S^2$  be such that  $p \in H_{w_0}^{\delta_1} = H_{w_0}^{\delta_2}$ . Note that  $K_{w_0}^{\delta_1}$  is a translation of  $L_{w_0}^{\delta_2}$  and both convex figures lie in the same plane. Furthermore, by definition,  $H_{w_0}^{\delta_1=\delta_2} \cap H_{x_0}^{\delta_1=\delta_2} \cap \text{int } K \neq \emptyset$ ,  $H_{w_0}^{\delta_1=\delta_2} \cap H_{x_0}^{\delta_1=\delta_2} \cap \text{int } L \neq \emptyset$ ,  $H_{w_0}^{\delta_1=\delta_2} \cap H_{y_0}^{\delta_1=\delta_2} \cap \text{int } K \neq \emptyset$ , and  $H_{w_0}^{\delta_1=\delta_2} \cap H_{y_0}^{\delta_1=\delta_2} \cap \text{int } L \neq \emptyset$ . Consequently, either  $\text{bd } K_{w_0}^{\delta_1} \cap \text{bd } L_{w_0}^{\delta_2}$  has more than three points or  $\text{bd } K_{w_0}^{\delta_1} \cap \text{bd } L_{w_0}^{\delta_2}$  has exactly two points that are the extreme points of a common diametral chord. In any case, since  $K_{w_0}^{\delta_1}$  is a translation of  $L_{w_0}^{\delta_2}$ , we have  $K_{w_0}^{\delta_1} = L_{w_0}^{\delta_2}$ ; therefore,  $p \in \text{bd } L$ . This completes the proof of the theorem.

**Theorem 1.2.** *Let  $K$  be a strictly convex body and let  $\delta$  be such that  $\{K_y^\delta\}_{y \in S^2}$  is a 2-cycle of sections of  $K$ . Suppose that, for every  $x \in S^2$ ,  $K_x^{\delta_1}$  is centrally symmetric. Then,  $K$  is centrally symmetric.*

**Proof.** Let  $\delta_1 = \delta$ ,  $L = -K$ , and  $\delta_2 = -\delta$ . Therefore, by hypothesis, for every  $x \in S^2$ , we have that  $L_x^{\delta_2} = -K_x^{\delta_1}$  is a translation of  $K_x^{\delta_1}$ . Consequently, by the above theorem,  $L = -K$  is a translation of  $K$ , which implies that  $K$  is centrally symmetric.

**Corollary 1.1.** *Suppose that  $K$  is a strictly convex body with the property that the hyperplane that divides the area (surface) in two is centrally symmetric. Then,  $K$  is centrally symmetric.*

**Corollary 1.2.** *Let  $K$  be a strictly convex body and let  $\delta$  be such that  $\{K_y^\delta\}_{y \in S^2}$  is a 2-cycle of sections of  $K$ . Suppose that, for every  $x \in S^2$ ,  $K_x^{\delta_1}$  is affinely equivalent to a fixed convex body  $L$ . Then,  $K$  is centrally symmetric.*

**Proof.** We follow the ideas and notation of [4]. As in the proof of Theorem 1 of [4], there is a complete turning of  $L$  in  $E^3$ . So, by Lemma 2 of [4],  $L$  is centrally symmetric; hence, by our Theorem 1.2,  $K$  is centrally symmetric.

## 2. ON THE BEZDEK CONJECTURE

Let  $K \subset E^3$  be a convex body. Suppose that every section of  $K$  is axially symmetric. Then, K. Bezdek conjectured that  $K$  must be a body of revolution or an ellipsoid. Consider two different and concentric circles in  $E^3$  of the same radius with center at the origin, and let  $K$  be the convex hull of these two circles. Then, it is not difficult to see that every section of  $K$  through the origin is axially symmetric. The purpose of this section is to prove the following theorem.

**Theorem 2.1.** *Let  $K \subset \mathbb{R}^3$  be a convex body and let  $p_0 \in \text{int } K$ . Suppose that every plane through  $p_0$  has an axis of symmetry. Then, there is a section of  $K$  through  $p_0$  that is a disk.*

First, we need a definition.

**Definition.** A collection of lines  $\{L_1, \dots, L_n\}$  is called an  $n$ -starline with vertex  $x_0$  if the lines  $L_i$  lie in a plane and are concurrent at  $x_0$  and the angle between two consecutive lines is  $\frac{2\pi}{n}$ . If  $H$  is a plane and  $L \subset H$  is a line through a point  $x_0$ , we denote by  $\text{st}_n(H, L, x_0)$  the unique  $n$ -starline with vertex  $x_0$  contained in  $H$  that has  $L$  as a member.

The following theorem is our main topology ingredient and follows immediately from the results of Mani in [3] (see also [4]).

**Theorem 2.2.** *Let  $1 \leq n < \infty$  be a positive integer. It is impossible to choose continuously, for every plane  $H$  through the origin in  $\mathbb{R}^3$ , an  $n$ -starline contained in  $H$  with vertex at the origin.*

**Proof.** A continuous selection of an  $n$ -starline for every plane through the origin in  $\mathbb{R}^3$  gives rise to a field of regular  $n$ -gons tangent to  $S^2$ , contradicting the main theorem of [3].

The proofs of the following results are straightforward and are left to the reader.

I. Let  $\Phi$  be a plane convex figure and let  $\{L_1, \dots, L_n\}$  be the collection of all its orthogonal lines of symmetry. Then,  $\{L_1, \dots, L_n\}$  is an  $n$ -starline.

II. Let  $K \subset \mathbb{R}^3$  be a convex body and let  $\{H_i\}$  be a sequence of planes that intersect  $\text{int } K$ . If  $H_i \rightarrow H$ , then  $H_i \cap K \rightarrow H \cap K$  in the Hausdorff metric.

III. Let  $K \subset \mathbb{R}^3$  be a convex body and let  $\{H_i\}$  be a sequence of planes that intersect  $\text{int } K$ . Suppose that  $H_i \rightarrow H$ ,  $L_i \subset H_i$  is an axial line of symmetry of  $H_i \cap K$ , and  $L_i \rightarrow L$ ; then, by II,  $L$  is an axial line of symmetry of  $H \cap K$ .

**Definition.** Let  $K$  be a convex body and let  $H$  be a plane that intersects  $\text{int } K$ . We say that  $\mu(H) = n$  if  $H \cap K$  has exactly  $n$  axial lines of symmetry. Note that  $\mu(H) = \infty$  implies that  $H \cap K$  is a disk.

IV. Let  $K \subset E^3$  be a convex body and let  $\{H_i\}$  be a sequence of planes that intersect  $K$ . If  $H_i \rightarrow H$  and  $\mu(H_i) \rightarrow \infty$ , then, by II,  $H \cap K$  is a disk.

**Proof of Theorem 2.1.** By IV, we may assume that  $1 \leq \mu(H) \leq n$  for every plane  $H$  through  $p_0$ . Let  $m = n!$ . For every plane  $\Gamma$  through the origin, let  $\text{st}_m \Gamma = \text{st}_m(\Gamma, L, 0)$ , where  $L$  is parallel to an axial line of symmetry of  $p_0 + \Gamma$ . Note that  $\text{st}_m \Gamma$  does not depend on the choice of the axial line of symmetry. We will prove that the function  $\Gamma \rightarrow \text{st}_m \Gamma$  is a continuous function. For this purpose, let  $\Gamma_i \rightarrow \Gamma$  and suppose that  $\text{st}_m \Gamma_i$  does not converge to  $\text{st}_m \Gamma$ . Then, there is a subsequence  $\Gamma_{i_j}$  such that  $\text{st}_m \Gamma_{i_j}$  converges to an  $m$ -starline  $\Omega$  contained in  $\Gamma$  with vertex 0, different

from  $\text{st}_m \Gamma$ . Let  $L_{i_j} \in \text{st}_m \Gamma_{i_j}$  be such that there is an axis of symmetry of  $(p_0 + \Gamma_{i_j}) \cap K$  parallel to  $L_{i_j}$ . We may assume, without loss of generality, perhaps by taking a subsequence, that  $L_{i_j} \rightarrow L$ . So,  $L \in \Omega$ , and therefore  $L \notin \text{st}_m \Gamma$ . But, by III,  $L$  is parallel to an axis of symmetry of  $(p_0 + \Gamma) \cap K$ , which is a contradiction. Therefore,  $\Gamma \rightarrow \text{st}_m \Gamma$  is continuous, contradicting Theorem 2.1.

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